Radio receiver

Wireless room sensors RAS-F starting with serial number 2286
and RAS-F/F starting with serial number 1222
and wireless radiation sensors GBS-F starting with serial number 1188
can only be used with radio receivers RCV-DL
starting with serial number 1867
**Function description**

The wireless system always comprises a transmitter (= e.g. wireless room sensor) and a receiver. The receiver can receive the signals from up to 8 transmitters.

The sensor sends the measurement values to the receiver every 10 minutes. If the measured values change by a defined difference, the values are immediately transmitted.

The receiver forwards the signals from the transmitters via the data link (DL bus) to the controller. With X2 controllers, they are applied as DL inputs; for the UVR1611 controller as network input variables (source: DL) and for the ESR31, UVR61-3, UVR63 and UVR63H controllers as external sensors.

With X2 controllers, there is a timeout if no value is transmitted after three queries by the controller. For controller UVR1611, time-out times can be defined for the DL network inputs (length: at least 10 minutes). If no information is received from the DL bus, the network error (X2 controllers) or network status (UVR1611) changes in the event of a time-out and the programming of the controller allows it to react to this interruption.

The receiver RCV-DL can be used with the following controllers:

- All controllers with X2 technology
- UVR1611 from version A3.00 and serial number 13286
- UVR63H from version 5.0
- UVR63 from version 1.0
- UVR61-3 from version 5.0
- ESR31 from version 1.0
**Coupling the receiver to the wireless sensor**

Push-buttons and 4 LEDs are used to couple the receiver to the particular wireless sensor. The 4 LEDs display a binary system, therefore:
- the first LED has the value 8,
- the second LED has the value 4,
- the third LED has the value 2 and
- the fourth LED the value 1.

Therefore a maximum of 15 addresses can be specified for wireless sensors.

<table>
<thead>
<tr>
<th>Address</th>
<th>1st LED Value 8</th>
<th>2nd LED Value 4</th>
<th>3rd LED Value 2</th>
<th>4th LED Value 1</th>
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<tbody>
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</tbody>
</table>

**Receiver (opened):**

4 display LED’s
Sequence from left to right: 8 4 2 1

Coupling button

DL bus connection
(Wires can be connected either way.)
Wire routing inside in the housing as short as possible!
Coupling instructions

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
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</thead>
<tbody>
<tr>
<td><strong>1</strong></td>
<td>Select a free address in the DL bus net</td>
</tr>
<tr>
<td><strong>2</strong></td>
<td>Press the receiver button for at least 2 seconds</td>
</tr>
<tr>
<td><strong>3</strong></td>
<td>Couple transmitter with receiver (see instruction of the transmitter)</td>
</tr>
</tbody>
</table>

Supplementary explanations:

1. A **free address** is selected by brief key presses at the receiver. A free **wireless address** can be identified because the relevant LEDs are permanently lit and do not flash. The same address cannot be used twice in the **DL bus network**. Thus for example, if address 1 is already occupied for a FTS4-50DL volume flow encoder, it cannot simultaneously be used for a wireless sensor.

2. After selecting the address, press the button for approximately 2 seconds -> the LEDs start to flash slowly at intervals of a second.

3. Couple the transmitter to the receiver
   The sensor send a coupling telegram to the receiver and "registers itself". **After successful registration, the LEDs start to flash more quickly after about 5 seconds.** The sensor must be coupled within a minute of the LEDs starting to flash slowly, otherwise the receiver switches back again (LEDs illuminate continuously). Likewise, coupling can be interrupted before registration of the transmitter by quickly pressing the receiver button.

Deleting an allocation

To delete the allocation of an address to a sensor, the corresponding address must be selected (LEDs flash quickly) and then the button pressed for at least 10 seconds until the LEDs switch over to continuous illumination.

Index specification

To process sensor values in the controller, specification and selection of the sensor address (1-15) and the index is necessary.

The values for the indices are given in the operating instructions for the radio sensors.

**X2 controllers:** The measured values are parameterised in the menu "**DL bus**".

**UVR1611:** The measurements are parameterised as **analog** network inputs:

- **NW.Node:** Sensor address
- **Anal.NW.Outp.:** Index of the measurement
- **Source:** DL
TAPPS2 - Programming UVR1611:

1. O14 Data Line

2. Analog network input

3. Source: DL

4. Sensor address

5. Index of the measured value

A still unused network input variable must be selected for each new value.

ESR31, UVR61-3, UVR63 and UVR63H:
Adjustment of the measurements takes place in the menu EXT DL (external sensors)

Example: External sensor 1 has address 1, the value of index 2 should be adopted.
This value can subsequently be allocated to a sensor value (menu ENTER/Men – SENSOR).

Table of settings

<table>
<thead>
<tr>
<th>Sensor No.</th>
<th>Address</th>
<th>Sensor serial number</th>
<th>Room</th>
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</table>

Power supply
The receiver is supplied directly from the DL-bus.
Important instruction for UVR1611: If CAN bus members are simultaneously fed from the controller, a 12V power pack (CAN-NT) must be used to aid in the power supply to these devices.
Installation

The receiver must only be installed in dry rooms.
The receiver has 2 fastening points for wall mounting.

Electrical connections RCV-DL

The receiver has to be connected to data link (DL-bus) and sensor mass. The connection polarity is unimportant.
Any cable with a cross section of 0.75 mm² can be used for the data link (e.g. twin-strand) having a max. length of 30 m. For longer cables, we recommend the use of shielded cable.

Dimensions in mm:

![Dimensions Diagram]

Technical data

- **Bus load of receiver:** 43%
- **Radio frequency:** 868.5 MHz
- **Range in the open air:** max. 1000m
- **Range in buildings:** typically 30m, 2 walls or ceilings (dependent on the wall thickness and material)
- **Protection class:** IP40

We reserve the right to make technical changes. © 2017
EU Declaration of conformity

Document- Nr. / Date: TA17057 / 02/02/2017
Company / Manufacturer: Technische Alternative RT GmbH
Address: A- 3872 Amaliendorf, Langestraße 124

This declaration of conformity is issued under the sole responsibility of the manufacturer.

Product name: RCV-DL
Product brand: Technische Alternative RT GmbH
Product description: Radio receiver

The object of the declaration described above is in conformity with Directives:
2014/53/EU Radio equipment (RED)
2011/65/EU RoHS Restriction of the use of certain hazardous substances

Employed standards:
EN 60730-1: 2011 Automatic electrical controls for household and similar use – Part 1: General requirements
EN 61000-6-3: 2007 Electromagnetic compatibility (EMC) - Part 6-3: Generic standards - Emission standard for residential, commercial and light-industrial environments
   + A1: 2011
   + AC2012
EN 61000-6-2: 2005 Electromagnetic compatibility (EMC) - Part 6-2: Generic standards - Immunity for industrial environments
   + AC2005
EN 50581: 2012 Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances

Position of CE - label: On packaging, manual and type label

Issuer: Technische Alternative RT GmbH
A- 3872 Amaliendorf, Langestraße 124

This declaration is submitted by

Dipl.-Ing. Andreas Schneider, General manager,
02/02/2017

This declaration certifies the agreement with the named standards, contains however no warranty of characteristics.
The security advices of included product documents are to be considered.
Guarantee conditions

Note: The following guarantee conditions do not in any way limit the legal right to a guarantee, rather expand your rights as a consumer.

1. The company Technische Alternative RT GmbH provides a two-year guarantee from the date of purchase by the end consumer for all the devices and parts which it sells. Defects must be reported immediately upon detection and within the guarantee period. Technical support knows the correct solution for nearly all problems. In this respect, contacting us immediately will help to avoid unnecessary expense or effort in troubleshooting.

2. The guarantee includes the free of charge repair (but not the cost of on site fault-finding, removal, refitting and shipping) of operational and material defects which impair operation. In the event that a repair is not, for reasons of cost, worthwhile according to the assessment of Technische Alternative, the goods will be replaced.

3. Not included is damage resulting from the effects of overvoltage or abnormal ambient conditions. Likewise, no guarantee liability can be accepted if the device defect is due to: transport damage for which we are not responsible, incorrect installation and assembly, incorrect use, non-observance of operating and installation instructions or incorrect maintenance.

4. The guarantee claim will expire if repairs or actions are carried out by persons who are not authorised to do so or have not been so authorised by us or if our devices are operated with spare, supplementary or accessory parts which are not considered to be original parts.

5. The defective parts must be sent to our factory with an enclosed copy of the proof of purchase and a precise description of the defect. Processing is accelerated if an RMA number is applied for via our home page www.ta.co.at. A prior clarification of the defect with our technical support is necessary.

6. Services provided under guarantee result neither in an extension of the guarantee period nor in a resetting of the guarantee period. The guarantee period for fitted parts ends with the guarantee period of the whole device.

7. Extended or other claims, especially those for compensation for damage other than to the device itself are, insofar as a liability is not legally required, excluded.

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